

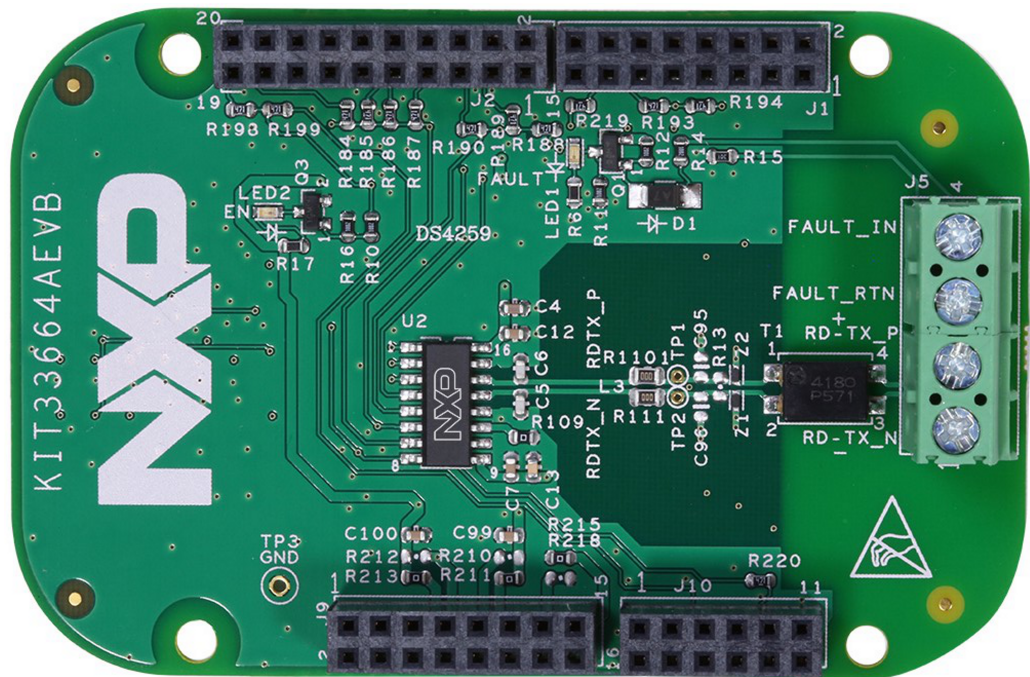
KT33664AEVBUG

KIT33664AEVB evaluation board

Rev. 2.0 — 25 October 2016

User guide

1 KIT33664AEVB



2 Important notice

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3 Getting started

3.1 Kit contents/packing list

The KIT33664AEVB contents include:

- Assembled and tested evaluation board/module in anti-static bag
- Quick start guide

The FRDM-33664AEVM contents include:

- Assembled and tested KIT33664AEVB evaluation board
- FRDM-KL25Z board
- Quick start guide

3.2 Jump start

NXP's analog product development boards provide an easy-to-use platform for evaluating NXP products. The boards support a range of analog, mixed-signal and power solutions. They incorporate monolithic ICs and system-in-package devices that use proven high-volume SMARTMOS technology. NXP products offer longer battery life, a smaller form factor, reduced component counts, lower cost and improved performance in powering state of the art systems.

1. Go to <http://www.nxp.com/KIT33664AEVB>.
2. Review your Tools Summary Page.
3. Locate and click:



4. Download the documents, software, and other information.

Once the files are downloaded, review the user guide in the bundle. The user guide includes setup instructions, BOM and schematics. Jump start bundles are available on each tool summary page with the most relevant and current information. The information includes everything needed for design.

3.3 Required equipment

The kit requires the following items:

- 5.0 V power supply, 50 mA capability
- 3.3 V power supply, 50 mA capability (If the application requires a 3.3 V logic threshold)
- Freedom board (optional)

4 Understanding the KIT33664AEVB

4.1 Board overview

The KIT33664AEVB and FRDM-33664AEVM are hardware evaluation tools that support system designs based on NXP’s MC33664ATL1EG device.

MC33664 is a transceiver physical layer transformer driver that links a microcontroller to a high speed isolated communication network. The transceiver converts SPI data bits into pulse bit information that is transferred to the bus network. Slave response messages use the same structure to send pulse bit information to the MC33664, which is then converted to a SPI bit stream and sent back to the MCU.

The MC33664 transceiver physical layer transformer driver can also convert MCU SPI data bits to pulse bit information for MC33771 and MC33772 devices being used in a BMS system.

4.2 Board features

The main features of the evaluation board are:

- MC33664 Isolated Communication Transceiver in a 16-pin SOICN package
- SPI interface
- LED indicators
- Fault detection report
- Isolated communication by transformers with connectors

4.3 Block diagram

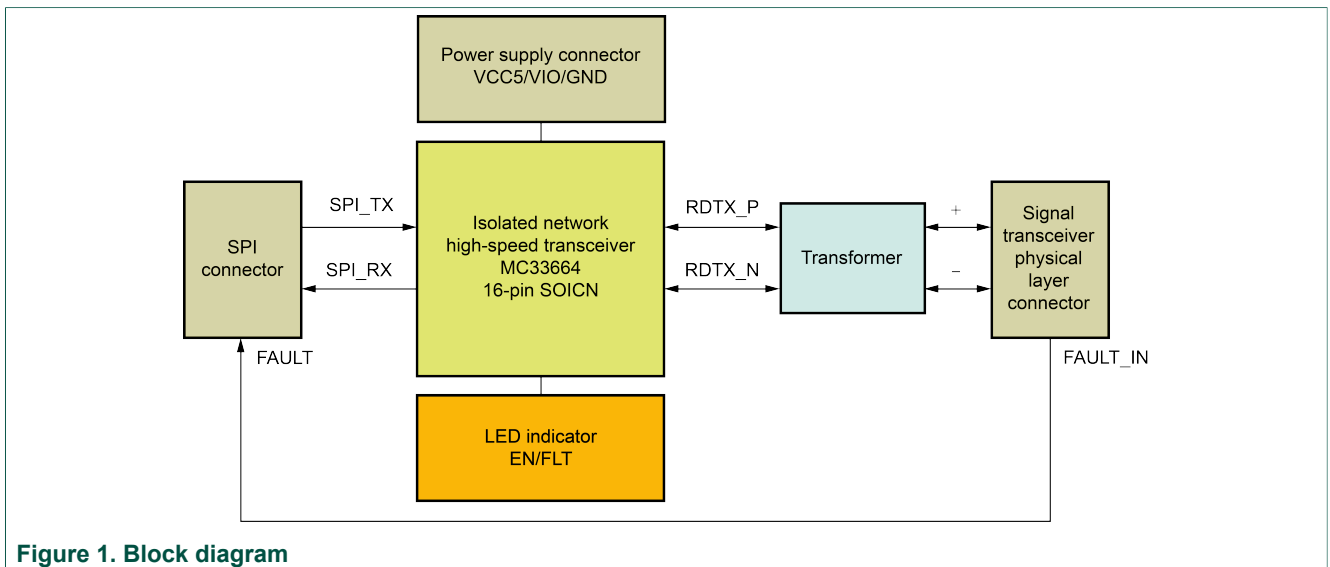


Figure 1. Block diagram

4.4 Device features

The MC33664 is an Isolated Communication Network High Speed Transceiver IC for managing isolated high speed differential communication. The device supports the following functions:

- 2.0 Mbps isolated network communication rate
- Dual SPI architecture for message confirmation
- Robust conducted and radiated immunity with wake-up
- 3.3 V and 5.0 V compatible logic thresholds
- Low sleep mode current with automatic bus wake-up
- Ultra-low radiated emissions

5 Getting to know the hardware

5.1 Board description

The KIT33664AEVB and FRDM-33664AEVM boards allow the user to exercise all the functions of the MC33664.

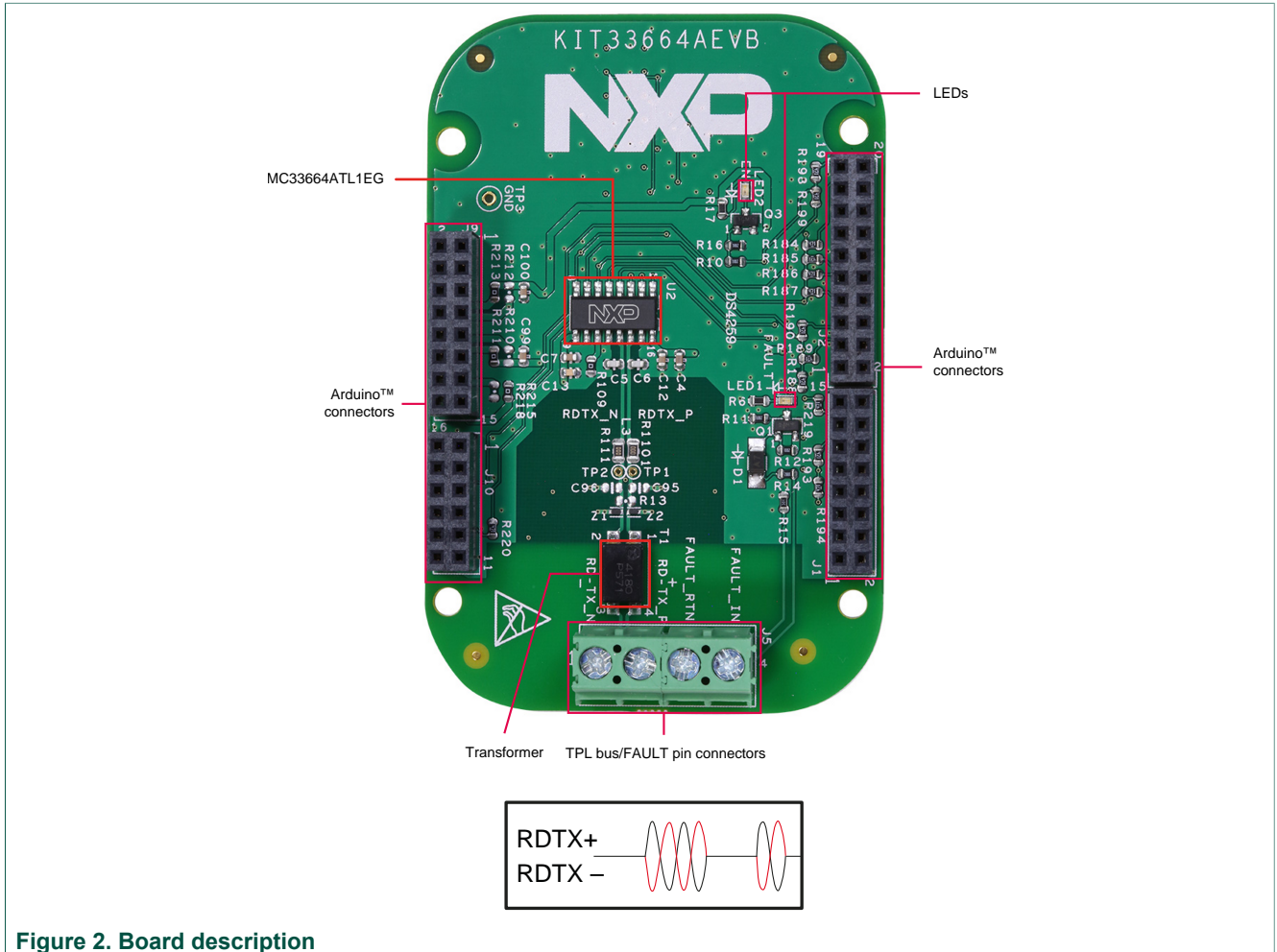


Table 1. Board description

Name	Description
LEDs	Indicators for on-board operations
Arduino™ connectors	Connectors for attaching a Freedom board and routing SPI signals and power lines
Transformer	Bus Isolator Transformer
TPL bus/ FAULT pin connector	Connector for TPL bus cables and FAULT pin connections
MC33664ATL1EG	Isolated Network High Speed Transceiver

5.2 LEDs

Figure 3 and Table 2 show the locations and description of the LEDs on the board.

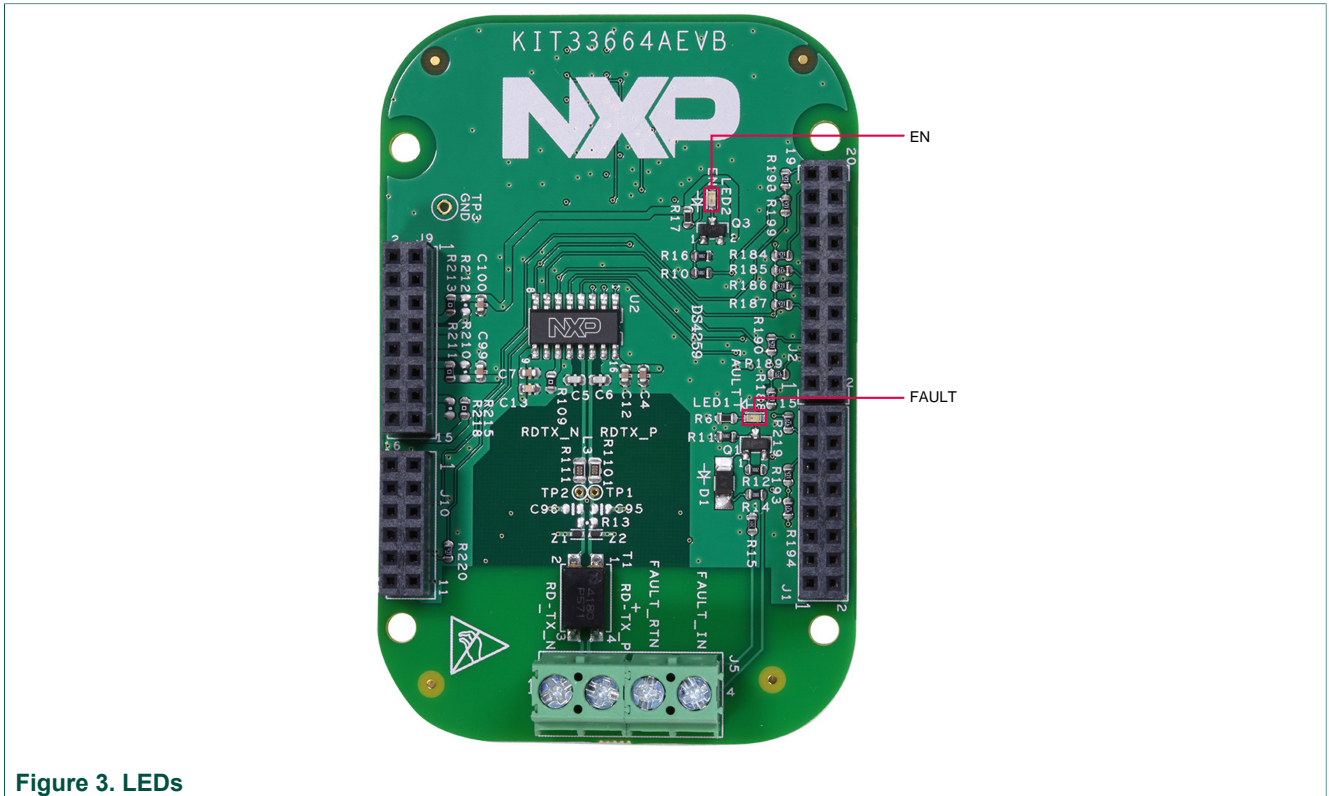


Figure 3. LEDs

Table 2. LEDs

LED Name	Description
EN	LED that indicates the operating mode. If the EN LED lights, the device is in normal operating mode. The device transmits and receives messages through SPI_TX for the transmission and SPI_RX for the reception. If the EN LED is off, the device is in sleep mode and no transmission is allowed. (See Table 3).
FAULT	Lights when the FAULT pin is set high (VIO) by the MCU

The MC33664 has the following modes of operation by the VIO and EN pins:

Table 3. Modes of operation

Device mode	EN pin	VIO pin	EN LED	Comment
Normal	1	1	On	The MC33664 operates as a full transceiver. MCU messages transmitted on the SPI_TX emerge on the SPI_RX for the MCU to read.
Sleep	0	1	Off	In sleep mode, the transceiver activates the INTB pin when a valid wake-up sequence is detected. The INTB pin remains low until the rising edge of the EN pin places the device in normal mode.

Device mode	EN pin	VIO pin	EN LED	Comment
Reset	—	0	Off	The RDTX± outputs are in high-impedance and the device is not able to transmit, receive, or report bus wake-up events

5.3 Test points

Figure 4 and Table 4 show the locations and description of test points on the board.

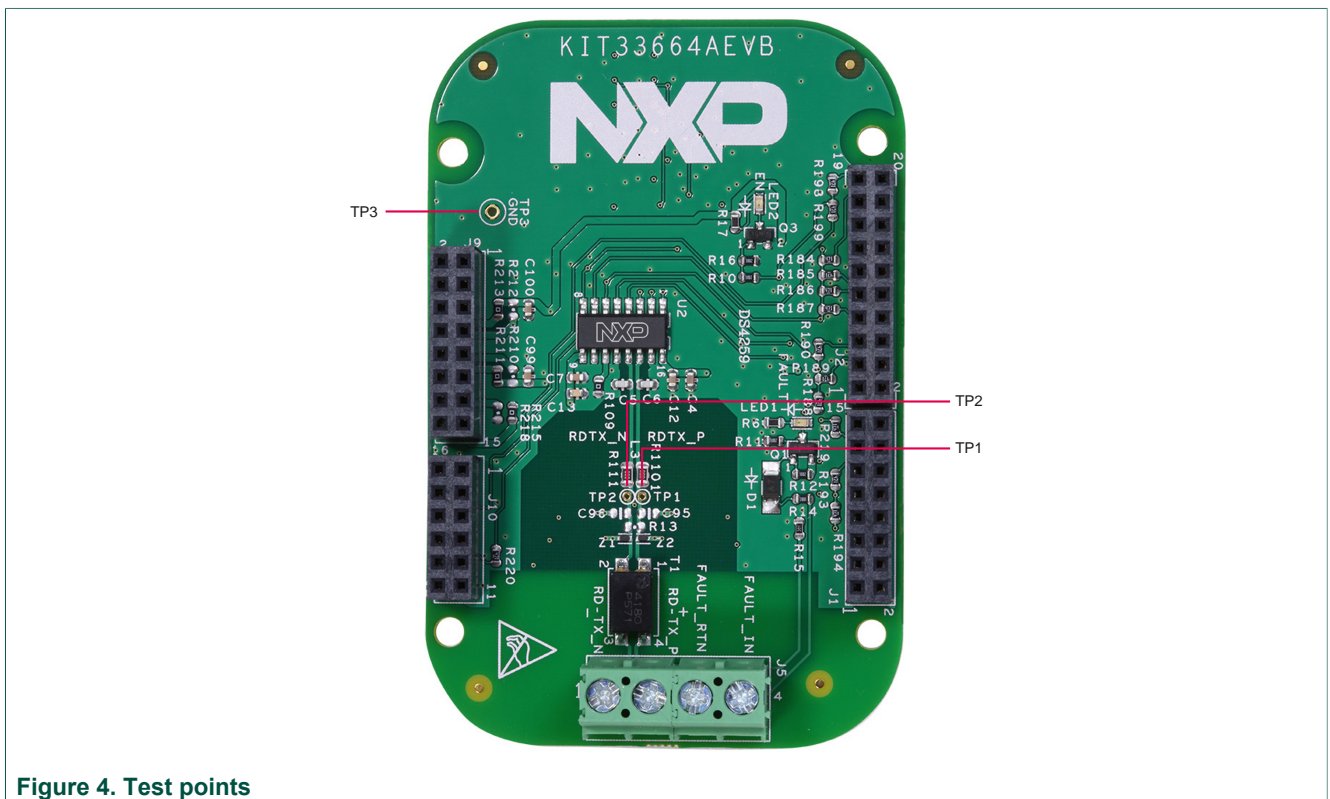


Figure 4. Test points

Table 4. Test points

Test point name	Signal name	Description
TP1	RDTX_P	RDTX_P Signal
TP2	RDTX_N	RDTX_N Signal
TP3	GND	Ground reference for the device

5.4 Connectors

Figure 5 shows the location of connectors on the board. Table 5 through Table 9 list the pin-outs for each connector.

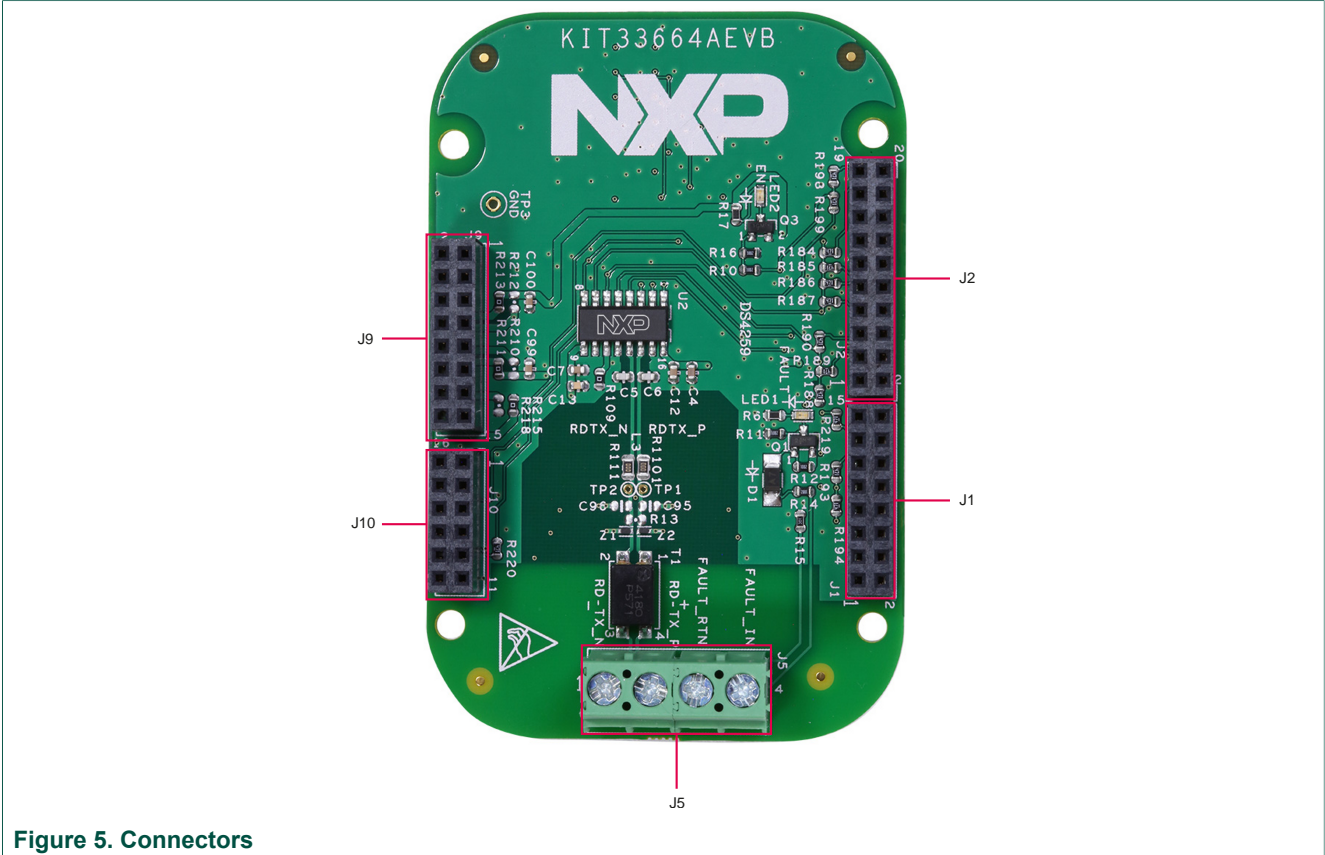


Figure 5. Connectors

Table 5. Connector J1

Pin #	Signal name	Description
1 to 16	—	Connections depend on configuration. See Table 10 and Table 11

Table 6. Connector J2

Pin #	Signal name	Description
1 to 20	—	Connections depend on configuration. See Table 10 and Table 11

Table 7. Connector J5

Pin #	Signal name	Description
1	RD_TX_N	TPL bus connection to the RDTX- pin (pin 13) on the isolated network high-speed transceiver device (MC33664)
2	RD_TX_P	TPL bus connection to the RDTX+ (pin 14) pin on the isolated network high-speed transceiver device (MC33664)
3	FAULT_RTN	TPL bus connection to FAULT_RTN
4	FAULT_IN	TPL bus connection to FAULT_IN

Table 8. Connector J9

Pin #	Signal name	Description
1 to 16	—	Connections depend on configuration. See Table 10 and Table 11

Table 9. Connector J10

Pin #	Signal name	Description
1 to 12	—	Connections depend on configuration. See Table 10 and Table 11

5.5 Signal bus terminal description

The transceiver (NET_N / NET_P) differential signal output is isolated by a transformer T1. Z1 and Z2 serve as ESD protection. All capacitors marked DNP are not populated on the board.

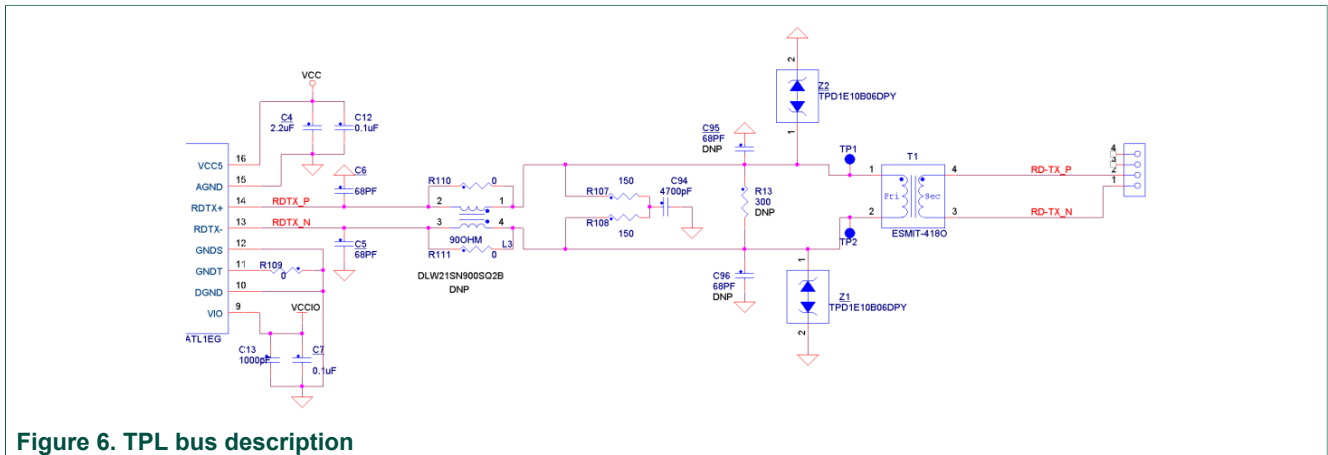


Figure 6. TPL bus description

6 Setting up the hardware

6.1 Fault input detection

An external low impedance connection (through a relay, optocoupler or similar components) between J5 – 3 (FAULT_RTN) and J5 – 4 (FAULT_IN) sets (VCCIO) the FAULT signal.

The FAULT signal alerts the MCU that an external FAULT condition has occurred. The FAULT signal is sent to the appropriate Freedom board pin or to pin J1-6 by default (see [Table 10](#)).

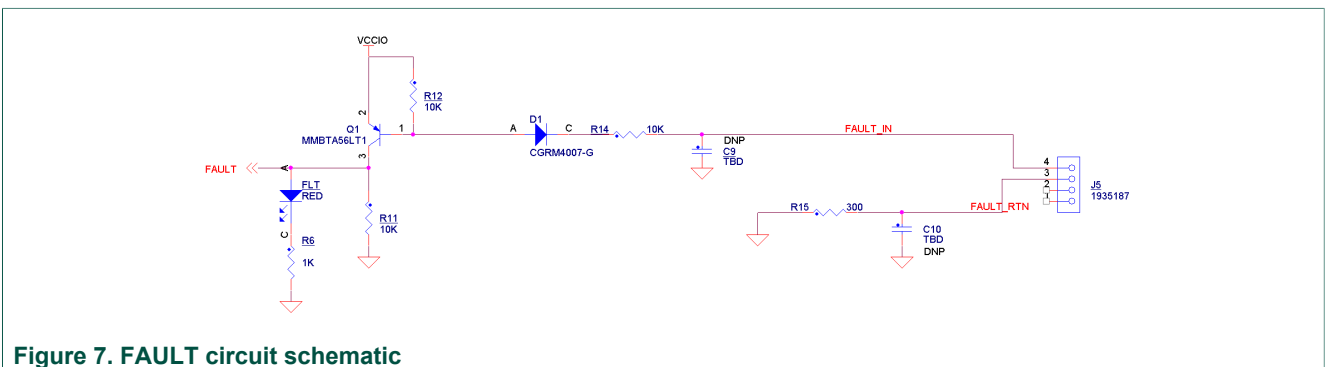


Figure 7. FAULT circuit schematic

7 Configuring the hardware

The KIT33664AEVB can be configured as a shield board connected to selected Freedom boards or it can be used in a stand-alone configuration (without a Freedom board).

7.1 Freedom board configuration

The KIT33664AEVB is compatible with the following Freedom evaluation boards:

- FRDM-KL25Z (Default factory setup configuration)
- FRDM-KV31F
- FRDM-KE06Z
- FRDM-KL43Z
- FRDM-KW40Z

The layout and the drill of the connectors allow all of these boards to be mounted directly to the KIT33664AEVB (see [Figure 8](#)). When both boards are connected together, the SPI connector is directly connected with the MCU SPI pins. The routing of SPI signals through the Arduino™ connectors depends on the specific Freedom board being used. In this configuration, power is supplied to the KIT33664AEVB through a USB cable connected between the Freedom board and a PC. No external power supply is required.



Figure 8. KIT33664AEVB mounted to a FRDM-KL25Z

The board must be modified to be compatible with each specific Freedom board. This modification consists of adding or removing shunts (0 Ω resistors) on the board. Most of the resistors are located on the bottom side of the board.

The tables below show the SPI signal routing and the KIT33664AEVB resistor modifications applicable to each board.

Table 10. KIT33664AEVB configuration table

Signal name	Connector pin	KL25Z (default configuration)	
		Add	Remove
FAULT	J1 – 6	R165	R208, R209
INTB	J1 – 8	R176	R202, R203
SCLK_TX	J1 – 9		
CSB_TX	J1 – 14		

	KL25Z (default configuration)		
DATA_TX	J2 - 8	R162	R161
SCLK_RX	J9 - 7		
CSB_RX	J9 - 5		
DATA_RX	J2 - 19		
EN	J2 - 18		

	KE06		
Signal name	Connector pin	Add	Remove
FAULT	J1 - 10	R170	R171
INTB	J3 - 10		
SCLK_TX	J1 - 8	R203	R202, R176
CSB_TX	J1 - 6	R209	R165, R208
DATA_TX	J1 - 12	R206	R207
SCLK_RX	J2 - 12		
CSB_RX	J2 - 6		
DATA_RX	J2 - 8	R161	R162
EN	J3 - 6		

	KL43		
Signal name	Connector pin	Add	Remove
FAULT	J1 - 8	R202	R203, R176
INTB	J4 - 10		
SCLK_TX	J1 - 15	R201	R200
CSB_TX	J1 - 6	R209	R165, R208
DATA_TX	J1 - 11	R204	R205
SCLK_RX	J2 - 12		
CSB_RX	J2 - 6		
DATA_RX	J2 - 8	R161	R162
EN	J4 - 6		

	KW40		
Signal name	Connector pin	Add	Remove
FAULT	J1 - 8	R202	R203, R176
INTB	J4 - 10		
SCLK_TX	J1 - 12	R207	R206
CSB_TX	J1 - 10	R171	R170
DATA_TX	J1 - 6	R208	R209, R165
SCLK_RX	J2 - 12		

	KW40		
CSB_RX	J2 - 6		
DATA_RX	J2 - 8	R161	R162
EN	J4 - 6		

	KV31		
Signal name	Connector pin	Add	Remove
FAULT	J1 -8	R202	R203, R176
INTB	J4 - 10		
SCLK_TX	J1 - 11	R205	R204
CSB_TX	J1 - 6	R209	R165, R208
DATA_TX	J1 - 13		
SCLK_RX	J2 - 12		
CSB_RX	J1 - 15	R200	R201
DATA_RX	J2 - 10		
EN	J4 - 6		

7.1.1 Step-by-step instructions for setting up the hardware in a Freedom board configuration

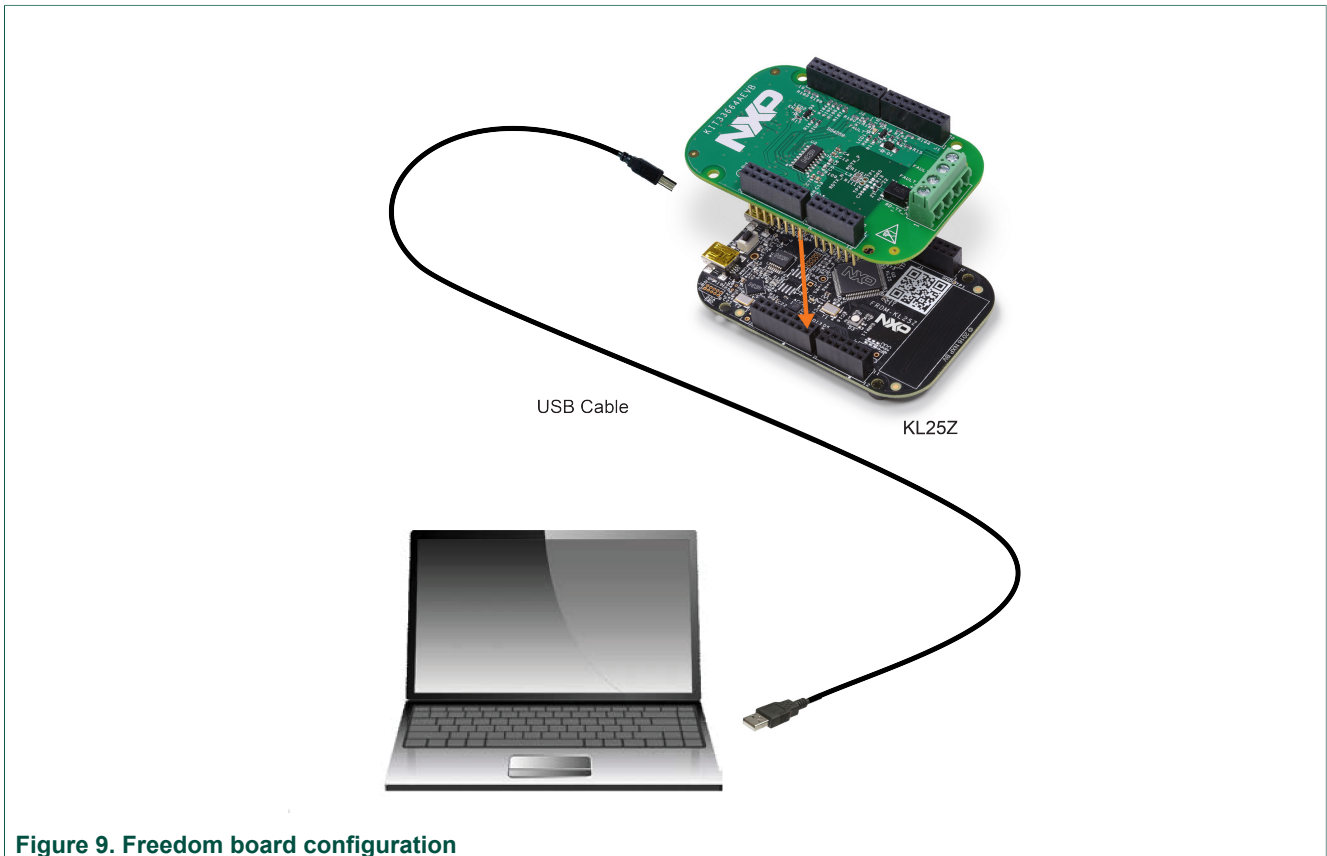


Figure 9. Freedom board configuration

Figure 9 shows the board configured for use with a Freedom board. The process for configuring the hardware is as follows:

1. Mount the KIT33664AEVB to the surface of the Freedom board by means of the on-board Arduino™ connectors (connectors J1, J2, J9 and J10).
2. Connect a USB cable between a PC and the USB port on the Freedom board. The KIT33664AEVB board draws power through the USB connection.

Microcode must be loaded onto the Freedom board to enable the exercising of board functions. For the Freedom-KL25Z, the microcode is included as a .srec file that is included with the KIT33664AEVB zip file. For other Freedom boards, the user must develop and download their own microcode to the Freedom board.

7.2 Standalone configuration

When the board is used in standalone mode, the SPI signals must be manually connected to connectors J1, J2 and J9 on the board.

Table 11. Standalone configuration table

Signal	Pin
FAULT	J1 – 6
INTB	J1 – 8
SCLK_TX	J1 – 9
CSB_TX	J1 – 14
DATA_TX	J2 – 8
SCLK_RX	J9 – 7
CSB_RX	J9 – 5
DATA_RX	J2 – 19
EN	J2 – 18

Power supply connections to the KIT33664AEVB are:

- VCC (5.0 V): J9 – 10
- VCCIO (3.3 V or 5.0 V depending on the required communication signal levels): J9 – 8
- GND: J9 – 12, J9 – 14, J2 – 14

7.2.1 Step-by-step instructions for setting up the hardware

When used in a standalone configuration, the power, ground, SPI signals and TPL signals must be manually attached to the board.

Figure 10 shows the KIT33664AEVB in standalone configuration.

Note: Users who are not fully knowledgeable in NXP MCU's and the Freedom board architecture should avoid using standalone mode.

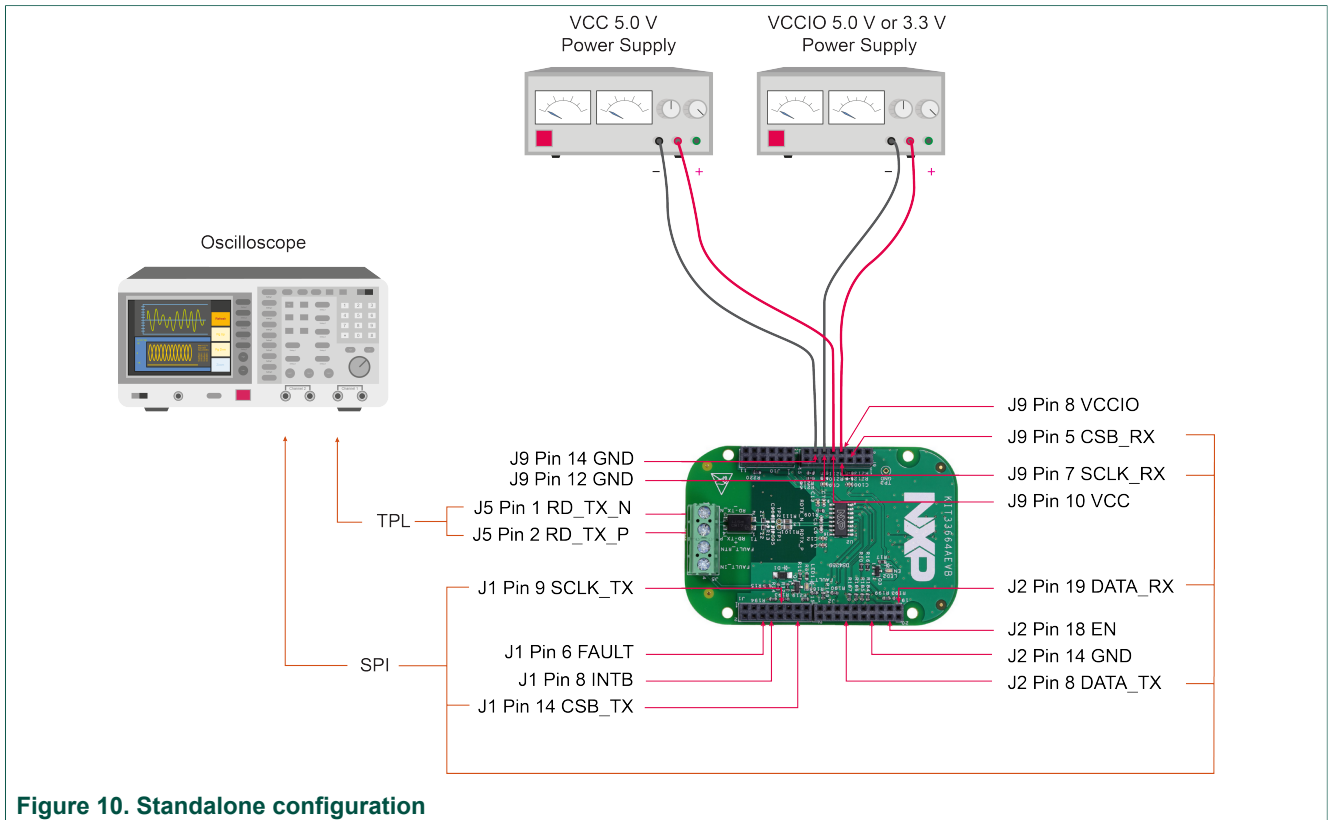


Figure 10. Standalone configuration

The process for configuring the hardware is as follows:

1. On the KIT33664AEVB, physically connect the SPI bus communication signals to the appropriate positions on connectors J1, J2 and J9 (see [Table 10](#)).
2. Connect the TPL signals to connector J5 (see [Table 7](#)).
3. Connect VCC to the 5.0 V power supply as follows:
 - Make sure that the power supply is switched off.
 - Connect the power supply's positive terminal to Pin 10 on Connector J9.
 - Connect the power supply's negative terminal to Pin 14 on Connector J9.
4. Connect VCCIO to either a 5.0 V power supply or a 3.3 V power supply (depending on the communication signal requirements).
 - Make sure the power supply is switched off.
 - Connect the power supply's positive terminal to Pin 8 on Connector J9.
 - Connect the power supply's negative terminal to Pin 12 on Connector J9.
5. Connect the SPI signals (TX, RX, SCKLK, CSB) and the TPL signals (RDTX+, RDTX-) to an oscilloscope.
6. Observe the isolated differential signal and the SPI signal on the oscilloscope. [Figure 11](#) shows the protocol of the output signal on the IC pins.

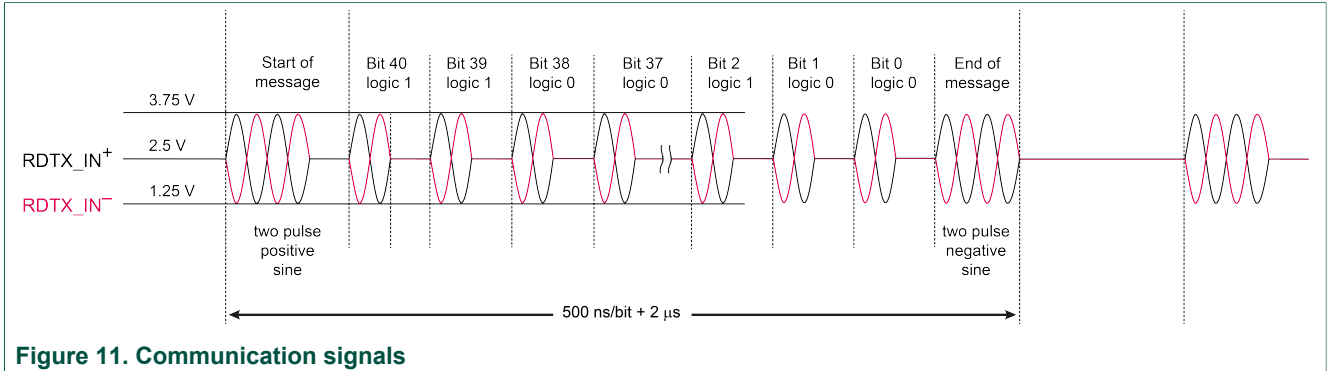


Figure 11. Communication signals

8 Schematic

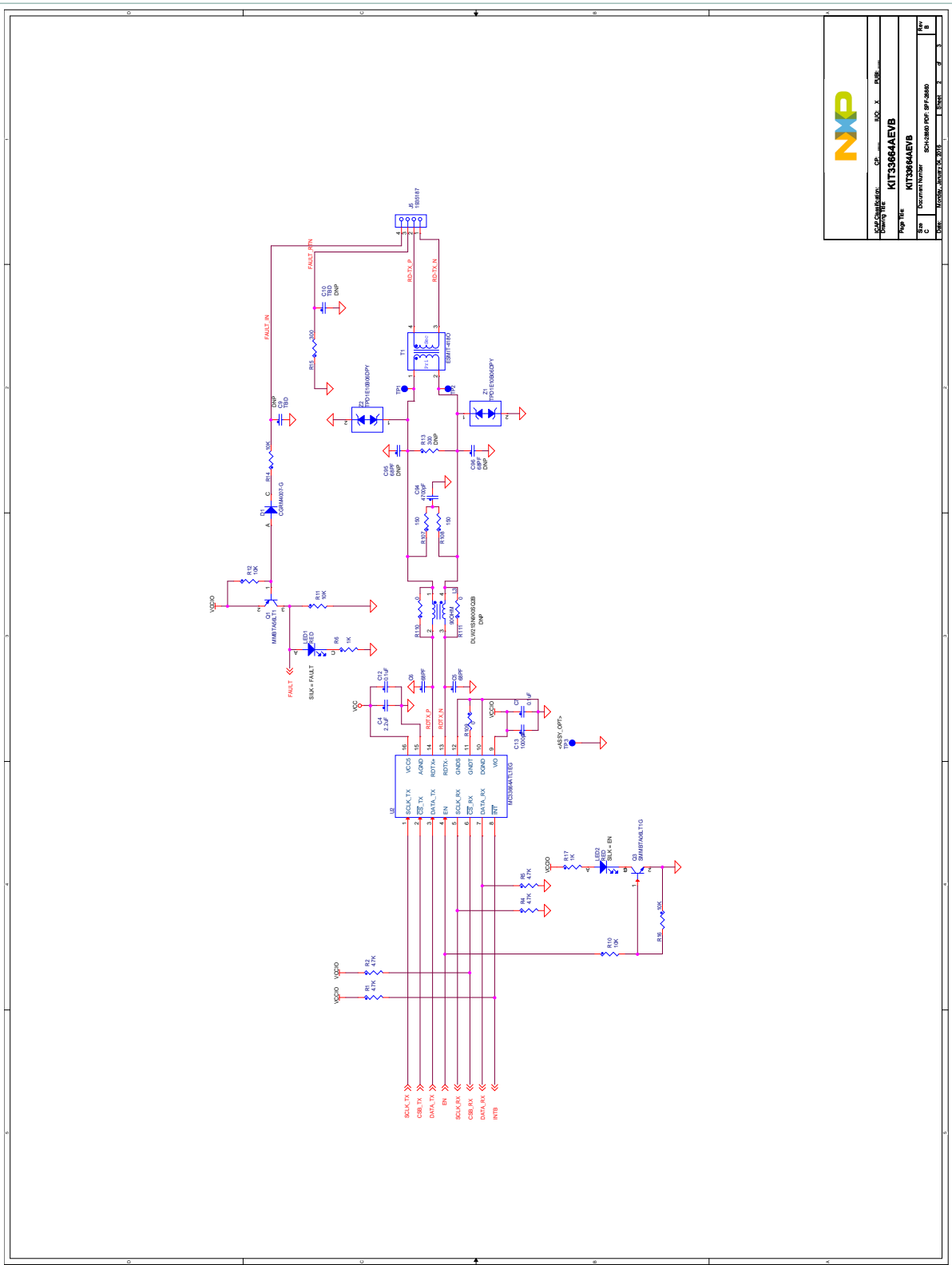


Figure 12. Schematic (a)

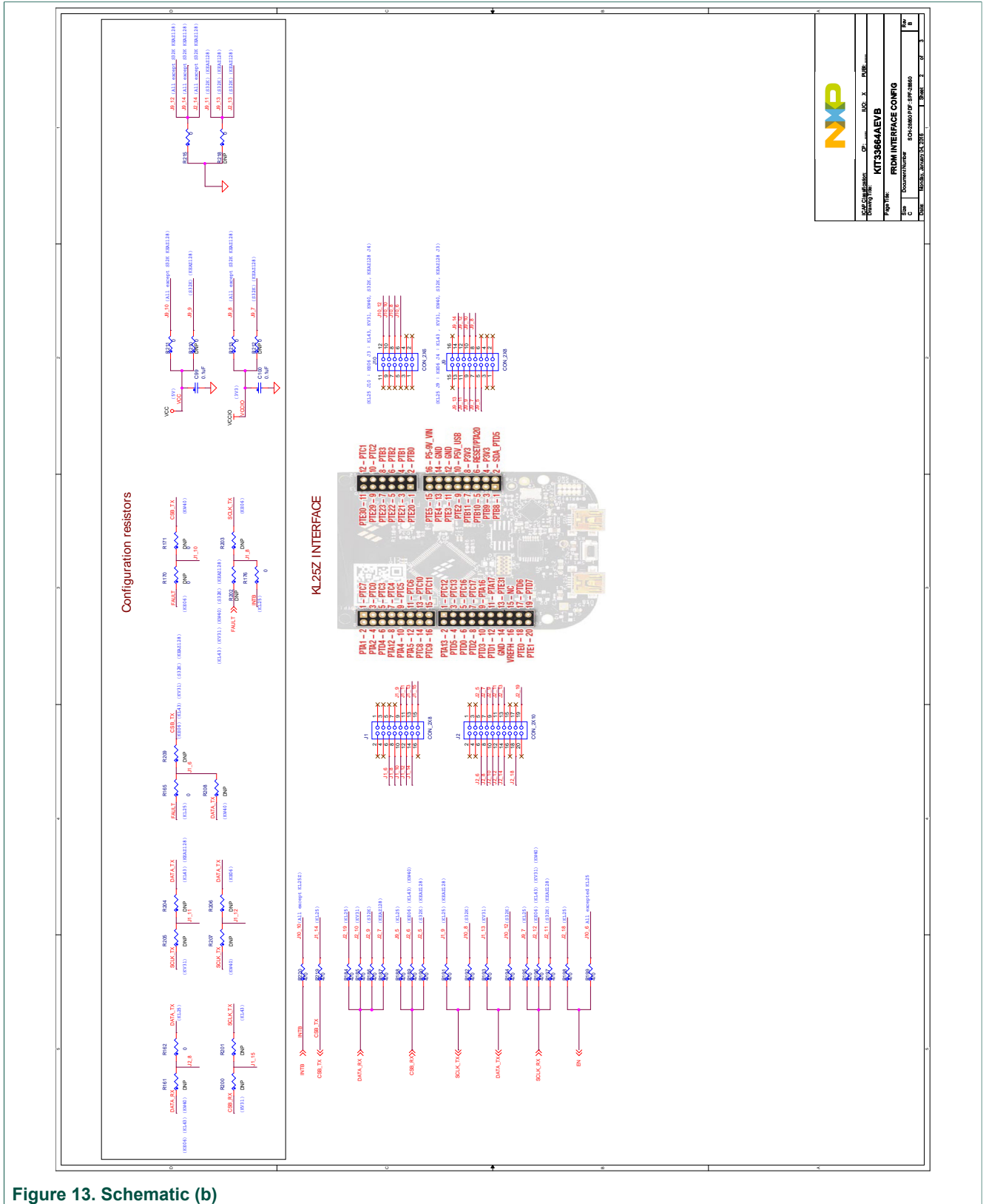


Figure 13. Schematic (b)

9 Board layout

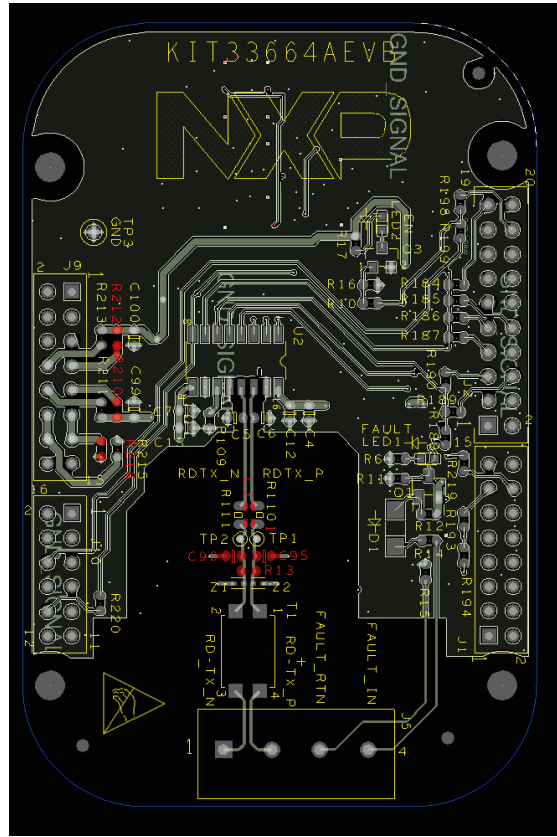


Figure 14. Top layer

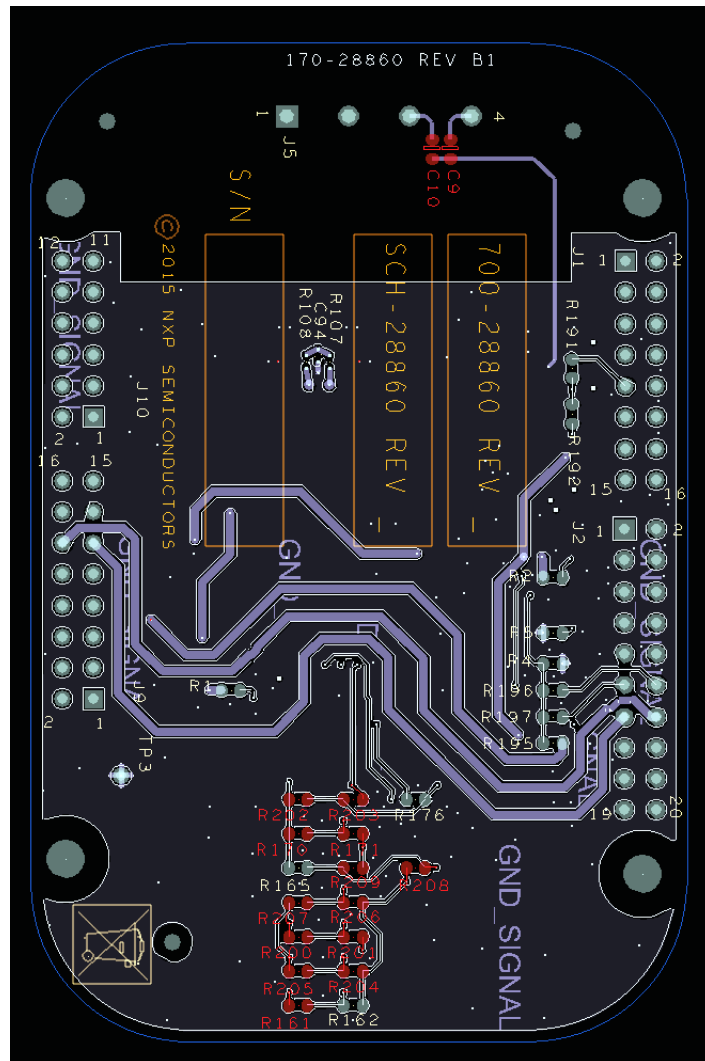


Figure 15. Bottom layer

10 Bill of materials

Table 12. Bill of Materials

Item	Qty	Schematic label	Value	Description	Part number	Assy opt
Integrated Circuits [1]						
1	1	U2	-	Isolated Network High Speed Transceiver 16-Pin SOICN - NXP	MC33664ATL1EG	-
2	2	Z1, Z2	-	ESD Protection diode 0402	TPD1E10B06DPY	-
3	1	T1	120 μ H	Transformer	ESMIT-4180/C	-
Transistors [1]						
4	1	Q1	-	Driver Transistor PNP 80V SOT23	MMBTA56LT1G	-
5	1	Q3	-	Driver Transistor NPN 80V SOT23	SMMBTA06LT1G	-
Diodes [1]						
6	1	D1	-	Diode General purpose 1kV 1A SOD123	CGRM4007-G	-
LEDs [1]						
7	2	FLT, EN	-	LED 630 nm RED 0603 SMD	SML-311UTT86	-
Capacitors [1]						
8	2	C5, C6	68 pF	50 V Capacitor C0603	-	-
9	1	C4	2.2 μ F	6.3 V Capacitor C0603	-	-
10	4	C7, C12, C99, C100	100 nF	50 V Capacitor C0603	-	-
11	1	C13	1 nF	50 V Capacitor C0603	-	-
12	1	C94	4.7 nF	50 V Capacitor C0603	-	-
13	7	C9, C10, C95, C96	-	Capacitor C0603	-	[2]
Resistors [1]						
14	4	R1, R2, R4, R5	4.70 k Ω	Resistor R0603	-	-
15	2	R6, R17	1.0 k Ω	Resistor R0603	-	-
16	4	R10, R11, R12, R14	10 k Ω	Resistor R0603	-	-
17	1	R15	300 Ω	Resistor R0603	-	-
18	2	R107, R108	150 Ω	Resistor R0402	-	-
19	7	R109, R162, R165, R176, R211, R213, R215	0 Ω	Resistor R0603	-	-
20	2	R110, R111	0 Ω	Resistor R0805	-	-
21	18	R184, R185, R186, R187, R188, R189, R190, R191, R192, R193, R194, R195, R196, R197, R198, R199, R219, R220	470 Ω	Resistor R0603	-	-

Item	Qty	Schematic label	Value	Description	Part number	Assy opt
22	17	R13, R161, R170, R171, R200, R201, R202, R203, R204, R205, R206, R207, R208, R209, R210, R212, R218	-	Resistor R0603	-	[2]
Switches, connectors, jumpers and testpoints						[1]
23	1	J5	-	Connector Terminal block 4POS 5.08MM PCB	1935187	-
24	2	J1, J9	-	CON2X8	SSQ-108-23-G-D	-
25	1	J2	-	CON2X10	SSQ-110-23-G-D	-
26	1	J10	-	CON2X6	SSQ-106-23-G-G	-

[1] NXP does not assume liability, endorse, or warrant components from external manufacturers that are referenced in circuit drawings or tables. While NXP offers component recommendations in this configuration, it is the customer's responsibility to validate their application.

[2] Do Not Populate

11 References

Table 13. References

NXP support pages	Description	URL
KIT33664AEVB	Tool Summary Page	http://www.nxp.com/KIT33664AEVB
MC33664	Product Summary Page	http://www.nxp.com/MC33664
FRDM-KL25Z	Tool Summary Page	http://www.nxp.com/FRDM-KL25Z
FRDM-KV31F	Tool Summary Page	http://www.nxp.com/FRDM-KV31F
FRDM-KE06Z	Tool Summary Page	http://www.nxp.com/FRDM-KE06Z
FRDM-KL43Z	Tool Summary Page	http://www.nxp.com/FRDM-KL43Z
FRDM-KW40Z	Tool Summary Page	http://www.nxp.com/FRDM-KW40Z

12 Revision history

Revision	Date	Description of changes
1.0	5/2016	Initial release
2.0	10/2016	Added kit contents for FRDM-33664AEVM

13 Contact information

Visit <http://www.nxp.com/support> for a list of phone numbers within your region.

Visit <http://www.nxp.com/warranty> to submit a request for tool warranty.

14 Legal information

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